

30/01/17]

1)

$$\sum_1^{\infty} a_n$$

$$a_n = \frac{n + \sqrt{n^2 + n}}{(n^2 + 1) (\sqrt{n^2 + n + 1})}$$

$$a_n \sim \frac{n^2 + o(n^2)}{n^3 \cdot n + o(n^4)} \sim \frac{1}{n^2}$$

termini di serie conv.

Ricordiamo:

$$\sum \frac{1}{n^\alpha \ln^p n}$$

$$\text{converge se } \begin{cases} \alpha > 1 & \forall p \\ \alpha = 1 & p > 1 \end{cases}$$

altrimenti diverge

$\sum a_n$ conv. assolutamente e semplicemente

$$2) \quad f(\theta) = \begin{pmatrix} 2\theta \cos \theta \\ 2\theta \sin \theta \\ \theta^3/3 \end{pmatrix}$$

$$\theta \in [0, 2\pi]$$

$$L(f) = \int_0^{2\pi} |f(\theta)| d\theta =$$

$$f' = \begin{pmatrix} 2\cos \theta - 2\theta \sin \theta \\ 2\sin \theta + 2\theta \cos \theta \\ \theta^2 \end{pmatrix}$$

$$= \int_0^{2\pi} (4\cos^2 \theta + 4\theta^2 \sin^2 \theta - \cancel{8\theta \cos \theta \sin \theta} + 6\sin^2 \theta + 4\theta^2 \cos^2 \theta + \cancel{8\theta \sin \theta \cos \theta} + \theta^4)^{1/2} d\theta =$$

$$= \int_0^{2\pi} (4 + 4\theta^2 + \theta^4)^{1/2} d\theta =$$

$$= \int_0^{2\pi} (\theta^2 + 2) d\theta = \left[\frac{1}{3}\theta^3 + 2\theta \right]_0^{2\pi} =$$

$$= \frac{8}{3}\pi^3 + 4\pi$$

$$3) \quad f(x) = \begin{cases} \frac{x^4 + y^4}{x^2 + y^2} & x \neq 0 \\ 0 & x = 0 \end{cases}$$

Risolviamo:

f differenziabile in $\underline{x_0} \Rightarrow f$ derivabile in $\underline{x_0} \Rightarrow$
 $\Rightarrow f$ continua in $\underline{x_0}$

a) $f(x) \geq 0 \quad (0,0)$ è min f assoluto
 $\forall x \in \mathbb{R}^2$

b) $\lim_{x \rightarrow 0} f(x) \sim \frac{\overset{2}{p^4} (\sin^4 \theta + \cos^4 \theta)}{\cancel{p^2}} \xrightarrow{p \rightarrow 0} 0$
 coord. polari

f continua in $(0,0)$

c) $\frac{\partial f}{\partial x}(0) = \lim_{h \rightarrow 0} \frac{f(h,0) - f(0,0)}{h} \sim \frac{h^4}{h^2} \cdot \frac{1}{h} \sim h \rightarrow 0$

$\frac{\partial f}{\partial x}(0) = 0$

$\underline{0}_n \quad f(x,y) = f(y,x) \Rightarrow \frac{\partial f}{\partial y}(0) = 0$

$\nabla f(0) = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$

d)

Ricordiamo

f differenziabile in \underline{x}_0 : $\underline{v} = \begin{pmatrix} v_1 \\ v_2 \end{pmatrix}$

$$\frac{\partial f}{\partial \underline{v}}(\underline{x}_0) = v_1 \frac{\partial f}{\partial x}(\underline{x}_0) + v_2 \frac{\partial f}{\partial y}(\underline{x}_0)$$

(ma non vale il viceversa)

$$\underline{v} = \begin{pmatrix} a \\ b \end{pmatrix}$$

$$a^2 + b^2 = 1$$

$$\frac{\partial f}{\partial \underline{v}}(0) = \lim_{h \rightarrow 0} \frac{f(ha, hb) - f(0,0)}{h} \sim$$

$$\sim \frac{b^4 (a^4 + b^4)}{b^2 (a^2 + b^2)} \cdot \frac{1}{h} \sim h (a^4 + b^4) \rightarrow 0 \quad \forall a, b$$

e) $\lim_{\underline{x} \rightarrow \underline{0}} \frac{f(x,y) - f(0,0) - \underbrace{\nabla f(0,0)}_{T_0 f} \cdot \begin{pmatrix} x \\ y \end{pmatrix}}{\sqrt{x^2 + y^2}} \sim$

\sim coord. polari

$$\frac{\rho^4 (\sin^4 \vartheta + \cos^4 \vartheta)}{\rho^2 (\underbrace{\sin^2 \vartheta + \cos^2 \vartheta}_1) \rho} \sim \rho (\sin^4 \vartheta + \cos^4 \vartheta)$$

$\downarrow \rho \rightarrow 0$
0

f è differenziabile in $(0,0)$

$$b) \quad a) \quad \underline{F} = \begin{pmatrix} y^2 + x^2y \\ x^2 - xy^2 \end{pmatrix} = \begin{pmatrix} F_x \\ F_y \end{pmatrix}$$

Riconduciamo:

Il dot \underline{F} è semplicemente connesso

\underline{F} conservativo se \underline{F} irrotazionale

\underline{F} irrotazionale

$$\frac{\partial F_x}{\partial x} - \frac{\partial F_y}{\partial y} = 0$$

$$\frac{\partial F_x}{\partial y} = 2y + x^2$$

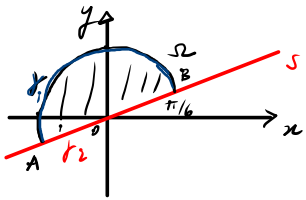
$$\frac{\partial F_y}{\partial x} = 2x - y^2$$

\underline{F} non è irrotazionale \Rightarrow

$\Rightarrow \underline{F}$ non conservativo

$$\underline{\nabla} \wedge \underline{F} = 2(y-x) + x^2 + y^2$$

$$b) \Omega = \{ z \in \mathbb{R}^2 : |z| \leq r, x \leq \sqrt{3}y \}$$



$$s: y \geq \frac{x}{\sqrt{3}}$$

$$A\left(-\frac{r\sqrt{3}}{2}, -\frac{r}{2}\right)$$

$$B\left(\frac{r\sqrt{3}}{2}, \frac{r}{2}\right)$$

$$c) \int_{\partial\Omega} f = \int_{\partial\Omega} \mathbb{F} \cdot d\mathbf{l}$$

$$L = \int_{\partial\Omega} \mathbb{F} \cdot d\mathbf{l}$$

$$j_1(\theta) = \begin{pmatrix} r \cos\theta \\ r \sin\theta \end{pmatrix}$$

$$\theta \in \left[\frac{\pi}{6}, \frac{\pi}{2}\right]$$

$$j_2(t) = \begin{pmatrix} t \\ t/\sqrt{3} \end{pmatrix}$$

$$t \in \left[-\frac{\sqrt{3}r}{2}, \frac{\sqrt{3}r}{2}\right]$$

$$L = \int_{j_1} \mathbb{F} \cdot d\mathbf{l} + \int_{j_2} \mathbb{F} \cdot d\mathbf{l}$$

$$j_1(\theta) = \begin{pmatrix} -r \sin\theta \\ r \cos\theta \end{pmatrix} \quad j_2(t) = \begin{pmatrix} 1 \\ 1/\sqrt{3} \end{pmatrix}$$

$$L = \int_{\frac{\pi}{6}}^{\frac{\pi}{2}} \mathbb{F}(r \cos\theta, r \sin\theta) \cdot j_1(\theta) d\theta + \int_{-\frac{\sqrt{3}r}{2}}^{\frac{\sqrt{3}r}{2}} \mathbb{F}(t, t/\sqrt{3}) \cdot j_2(t) dt \Rightarrow$$

$$\mathbb{F} = \begin{pmatrix} y^2 + x^2 y \\ x^2 - xy^2 \end{pmatrix}$$

$$\Rightarrow L = \int_{\frac{\pi}{6}}^{\frac{\pi}{2}} [(r^2 \sin^2\theta + r^3 \cos^2\theta \sin\theta) (-r \sin\theta) + \frac{r^2}{3} + (r^2 \cos^2\theta - r^3 \cos\theta \sin^2\theta) (r \cos\theta)] d\theta +$$

$$+ \int_{-\frac{\sqrt{3}r}{2}}^{\frac{\sqrt{3}r}{2}} \left[\left(\frac{t^2}{3} + \frac{t^3}{\sqrt{3}} \right) + \left(t^2 - \frac{t^3}{3} \right) \frac{1}{\sqrt{3}} \right] dt =$$

$$= r^3 \int_{\frac{\pi}{6}}^{\frac{\pi}{2}} (-\sin^3\theta - \cos^2\theta \sin^2\theta + \cos^3\theta - \cos^2\theta \sin^2\theta) d\theta +$$

$$+ \int_{-\frac{\sqrt{3}r}{2}}^{\frac{\sqrt{3}r}{2}} \left(\frac{t^2}{3} + \frac{t^3}{\sqrt{3}} + \frac{t^2}{\sqrt{3}} - \frac{t^3}{3\sqrt{3}} \right) dt =$$

Calculus complesso

Teor. di Stokes

$$L = \oint \underline{F} \cdot d\underline{s} = \int_{\Omega} \nabla \wedge \underline{F} \cdot d\underline{s}$$

$$L = \int_{\Omega} \left(\frac{\partial F_x}{\partial y} - \frac{\partial F_y}{\partial x} \right) \cdot d\underline{s} =$$

$$= \int_{\Omega} 2(y-x) + (x^2+y^2) \, dx \, dy =$$

$$= \int_{\Omega} (2\rho(\sin\theta - \cos\theta) + \rho^2) \rho \, d\rho \, d\theta =$$

$$dS = \rho \, d\rho \, d\theta$$

$$= \int_{\frac{\pi}{6}}^{\frac{7}{6}\pi} d\theta \int_0^r 2\rho^2(\sin\theta - \cos\theta) + \rho^3 \, d\rho =$$

$$= \int_{\frac{\pi}{6}}^{\frac{7}{6}\pi} (\sin\theta - \cos\theta) \frac{2}{3} \rho^3 \Big|_0^r \, d\theta + \int_{\frac{\pi}{6}}^{\frac{7}{6}\pi} \frac{1}{4} \rho^4 \Big|_0^r \, d\theta =$$

$$= \frac{2}{3} r^3 \left[-\cos\theta - \sin\theta \right]_{\frac{\pi}{6}}^{\frac{7}{6}\pi} + \frac{\pi}{4} r^4 =$$

$$= \frac{2}{3} r^3 \left[\frac{\sqrt{3}}{2} + \frac{1}{2} - \left(-\frac{\sqrt{3}}{2} - \frac{1}{2} \right) \right] + \frac{\pi}{4} r^4 =$$

$$= \frac{2}{3} r^3 (\sqrt{3} + 1) + \frac{\pi}{4} r^4$$

Risultati

$$\int_V \underline{F} \cdot d\underline{s} = \int_V \underline{\nabla} \cdot \underline{F} \, dV \quad \partial V = S$$

Gauss-Green

$$\oint_C \underline{F} \cdot d\underline{l} = \int_S \underline{\nabla} \wedge \underline{F} \cdot d\underline{s} \quad \partial S = C$$

Stokes

16/01/19]

$$1) \quad y'' - 4y' + 3y = 18t - 2e^t \quad \leftarrow \text{errore nel testo}$$

$$y = y_0 + \bar{y}$$

$$y_0: \quad \lambda^2 - 4\lambda + 3 = 0 \Rightarrow \lambda = 3 \vee \lambda = 1$$

$$y_0 = A e^t + B e^{3t}$$

$$\bar{y}: \quad \bar{y} = at e^t + bt + c$$

$$\bar{y}' = a e^t + at e^t + b$$

$$\bar{y}'' = a e^t + a e^t + at e^t$$

$$\underbrace{2a e^t} + \cancel{e^t e^t} - 4 \underbrace{a e^t} - \cancel{4at e^t} - \underbrace{4b}_x + 3 \underbrace{at e^t}_x + \underbrace{3bt}_x + \underbrace{3c}_x = \underbrace{18t}_x - \underbrace{2e^t}_x$$

$$\begin{cases} -2a = -2 \\ 3b = 18 \\ -4b + 3c = 0 \end{cases} \quad \begin{cases} a = 1 \\ b = 6 \\ c = \frac{4}{3}b = 8 \end{cases}$$

$$y = A e^t + B e^{3t} + t e^t + 6t + 8$$

$$2) \quad f(x,y) = xy e^{x-y}$$

$$\begin{cases} \frac{\partial f}{\partial x} = y e^{x-y} + xy e^{x-y} = 0 \\ \frac{\partial f}{\partial y} = x e^{x-y} - xy e^{x-y} = 0 \end{cases} \quad \begin{cases} y(1+x) = 0 \\ y + xy = 0 \\ x - xy = 0 \end{cases}$$

$$\left. \begin{cases} y=0 \\ x=0 \end{cases} \right\} \vee \left. \begin{cases} x=-1 \\ y=1 \end{cases} \right\} \begin{matrix} 0(0,0) \\ A(-1,1) \end{matrix}$$

$$\frac{\partial^2 f}{\partial x^2} = y e^{x-y} + y e^{x-y} + xy e^{x-y}$$

$$\frac{\partial^2 f}{\partial x \partial y} = (e^{x-y} - y e^{x-y})(x+1)$$

$$\frac{\partial^2 f}{\partial y^2} = -x e^{x-y} - x e^{x-y} + xy e^{x-y}$$

$$H_f(0,0) = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

$$\det H_f(0,0) = -1 < 0$$

$(0,0)$ sella dif

$$H_f(-1,1) = \begin{bmatrix} e^{-2} & 0 \\ 0 & +e^{-2} \end{bmatrix}$$

$$\det H_f(-1,1) = e^{-4} > 0$$

$$\text{tr } H_f(-1,1) = 2e^{-2} > 0$$

$A(-1,1)$ minif

Ricordiamo:

$$\det H_f(\underline{x}_0) < 0 \quad \text{sella}$$

$$\det H_f(\underline{x}_0) > 0$$

$$\begin{cases} \text{tr } (H_f(\underline{x}_0)) > 0 \\ \text{tr } (H_f(\underline{x}_0)) < 0 \end{cases} \quad \begin{matrix} \text{minif} \\ \text{maxif} \end{matrix}$$